

The Stability of Noisy Tilings in the Arithmetical Hierarchy

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Joint work with Mathieu Sablik

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Crash Course on Noisy Tilings

Stability for Periodic Tilings

Stability for Aperiodic Tilings

- The Robinson Tiling

- Aperiodic Stability

- Aperiodic Unstability

Undecidability of the Stability

- Σ_1 -Hardness of the Problem

- Climbing the Arithmetical Hierarchy

- Finding an Upper Bound

Crash Course on Noisy Tilings

Subshifts of Finite Type

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Figure 1: Example of configuration,

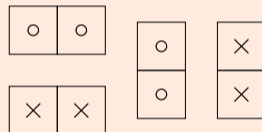
- Grid \mathbb{Z}^2 .
- Alphabet $\mathcal{A} = \{\circ, \times\}$.

Subshifts of Finite Type

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Figure 1: Example of configuration, without forbidden patterns.

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- Forbidden patterns \mathcal{F} :



Subshifts of Finite Type

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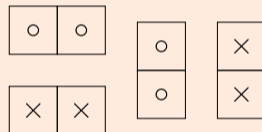


Figure 1: Example of configuration, without forbidden patterns.

The SFT is the space $\Omega_{\mathcal{F}} \subset \mathcal{A}^{\mathbb{Z}^d}$ of such configurations.

Denote $\mathcal{M}_{\mathcal{F}}$ the σ -invariant measures on $\Omega_{\mathcal{F}}$.

Clair-Obscur Framework

- Inject $\mathcal{A} \hookrightarrow \tilde{\mathcal{A}} = \mathcal{A} \times \{0, 1\}$.
- Identify $\mathcal{F} \cong \tilde{\mathcal{F}} = \mathcal{F} \times \{0\}$.
- Denote $\widetilde{\mathcal{M}}_{\tilde{\mathcal{F}}}^{\mathcal{B}}(\varepsilon) \subset \mathcal{M}_{\tilde{\mathcal{F}}}$ the measures with $\mathcal{B}(\varepsilon)^{\otimes \mathbb{Z}^d}$ Bernoulli noise.
- The set $\widetilde{\mathcal{M}}_{\tilde{\mathcal{F}}}^{\mathcal{B}}(\varepsilon)$ is weak- $*$ closed, and $\bigcap_{\varepsilon > 0} \widetilde{\mathcal{M}}_{\tilde{\mathcal{F}}}^{\mathcal{B}}(\varepsilon) = \mathcal{M}_{\mathcal{F}}$.

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Figure 2: Configuration,

Clair-Obscur Framework

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Figure 2: Configuration, now with obscured cells.

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Figure 2: Configuration, now with obscured cells.

Reminder (Weak- * Convergence)

We say that $\mu_n \xrightarrow{*} \mu$ when $\mu_n([w]) \rightarrow \mu([w])$ for any finite pattern w .

Besicovitch Distance

x

×	○	×	○	×	○	×	○	×	○	×	○	×
○	○	×	○	○	×	×	○	×	○	×	○	×
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Finite Hamming distance:

$$d_{13 \times 8}(x, y) = \frac{13}{13 \times 8}$$

Figure 3: Frequency of differences between x and y.

Besicovitch Distance

y

×	○	×	○	×	○	×	○	×	○	×	○	×
○	×	○	×	○	×	○	×	○	×	○	×	○
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○	×	○	×	○	×	○	×	○	×	○	×	○
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○	×	○	×	○	×	○	×	○	×	○	×	○

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$$d_{13 \times 8}(x, y) = \overline{13 \times 8}$$

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Besicovitch Distance

$x|y$

×	○	×	○	×	○	×	○	×	○	×	○	×
○	⊗	⊗	⊗	○	×	⊗	⊗	⊗	⊗	⊗	⊗	⊗
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○	×	○	×	○	×	⊗	×	⊗	×	○	×	○

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Besicovitch Distance

$x|y$

×	○	×	○	×	○	×	○	×	○	×	○	×
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$$d_H = \limsup_{n \rightarrow \infty} d_{n \times n}$$

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Besicovitch Distance

		x y												
	x	×	○	×	○	×	○	×	○	×	○	×	○	×
	y	○	⊗	⊗	⊗	○	×	⊗	⊗	⊗	⊗	⊗	⊗	⊗
	x	×	○	⊗	○	⊗	○	×	⊗	⊗	○	×	○	×
	y	○	×	⊗	×	○	×	○	×	○	×	○	×	○
	x	×	○	×	⊗	×	⊗	⊗	○	⊗	○	⊗	○	×
	y	○	⊗	⊗	×	⊗	×	○	×	○	⊗	⊗	⊗	⊗
	x	×	⊗	×	○	×	○	⊗	⊗	×	○	⊗	○	×
	y	○	×	○	×	○	×	⊗	×	⊗	×	○	×	○

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Besicovitch distance on σ -invariant measures:

$$d_B(\mu, \nu) = \inf_{\lambda \text{ a coupling}} \int d_H(x, y) d\lambda(x, y)$$

Stability

The SFT $\Omega_{\mathcal{F}}$ is f -stable for d_B on Bernoulli noises if:

$$\forall \varepsilon > 0, \quad \sup_{\lambda \in \widetilde{\mathcal{M}}_{\mathcal{F}}^B(\varepsilon)} d_B(\pi_1^*(\lambda), \mathcal{M}_{\mathcal{F}}) \leq f(\varepsilon).$$

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Theorem [Gayral and Sablik, 2021, Corollary 3.15]

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What kind of (in)stability results can we expect from typical SFTs?

A fixed-point argument [Durand et al., 2012] already gave a stable aperiodic example.

Stability for Periodic Tilings

1D Classification of the Stability

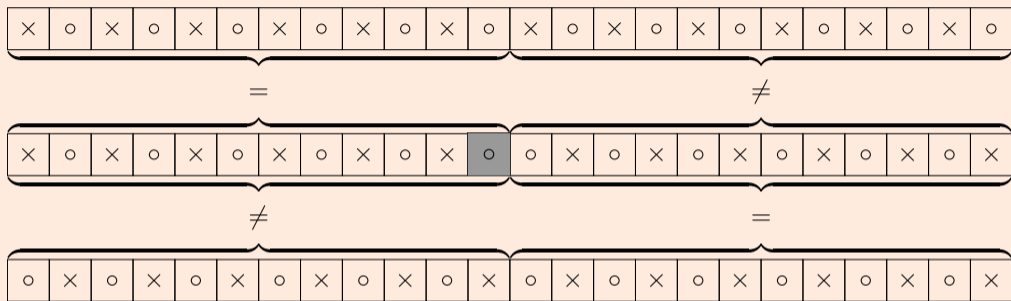


Figure 4: The noisy configuration is at Hamming distance $\frac{1}{2}$ of the clear ones.

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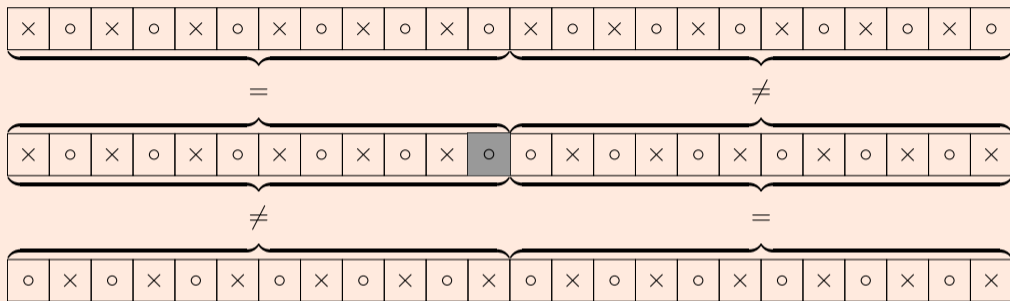


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Theorem [Gayral and Sablik, 2021, Theorem 4.8 and Theorem 4.9]

Consider $\Omega_{\mathcal{F}}$ a 1D SFT. Then $\Omega_{\mathcal{F}}$ is (linearly) stable on Bernoulli noises iff it is mixing.

Most notably, p -periodic SFTs (with $p \geq 2$) are unstable.

Periodic Tilings in Higher Dimensions

A SFT $\Omega_{\mathcal{F}}$ is (strongly) periodic if there exists an integer N such that any configuration is invariant for any translation in $(N\mathbb{Z})^d$.

Theorem [Gayral and Sablik, 2021, Theorem 5.7]

Consider $\Omega_{\mathcal{F}}$ a $2D+$ periodic SFT.

Then $\Omega_{\mathcal{F}}$ is f -stable on Bernoulli noises, with linear speed $f(\varepsilon) = 2C_{c(\mathcal{F})}^d \varepsilon$.

Reconstruction Function

Lemma [Gayral and Sablik, 2021, Lemma 5.3]

Consider a $2D+$ periodic SFT $\Omega_{\mathcal{F}}$.

There exists $c(\mathcal{F}) \geq \lceil \frac{N}{2} \rceil$ such that, for any connected cell window $I \subset \mathbb{Z}^d$, if $w \in \mathcal{A}^{I+B_c}$ is locally admissible, then $w|_I$ is globally admissible.

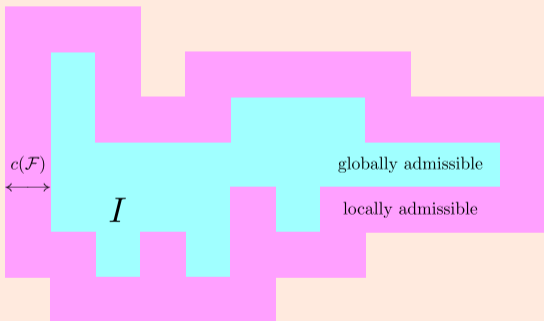


Figure 5: Here, the whole domain contains no forbidden pattern, but only the blue zone is guaranteed to be the restriction of an actual configuration.

Thickened Percolation

Consider $\varphi_n(b)_x = \max_{\|y-x\|_\infty \leq n} b_y$ for $b \in \{0, 1\}^{\mathbb{Z}^d}$.

Starting from a site percolation ν , we obtain the n -thickened percolation $\varphi_n^*(\nu)$.

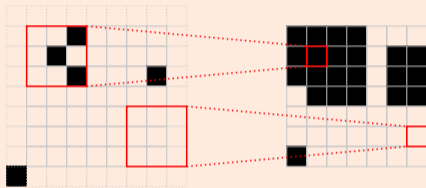


Figure 6: Illustration of the mapping φ_1 .

Proposition [Gayral and Sablik, 2021, Proposition 5.6]

Consider $I \subset \mathbb{Z}^d$ the random infinite component of the n -thickened $\mathcal{B}(\varepsilon)^{\otimes \mathbb{Z}^d}$ -percolation.

Then $C_n^d = 48(2n + 1)^d$ is such that $\mathbb{P}(0 \notin I) \leq C_n^d \times \varepsilon$.

Stability for Aperiodic Tilings

The Robinson Tiling

The (Enhanced) Robinson Tiling

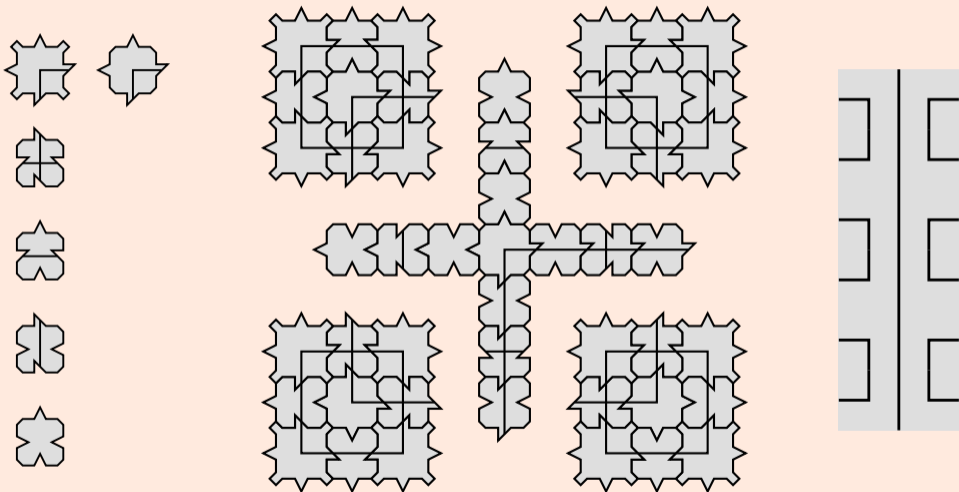


Figure 7: Tileset and hierarchical structure of the Robinson tiling,

The (Enhanced) Robinson Tiling

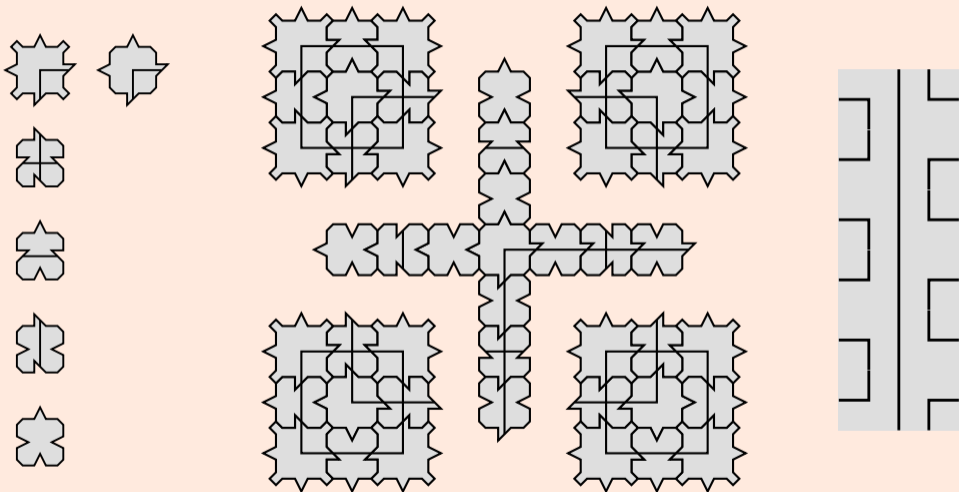


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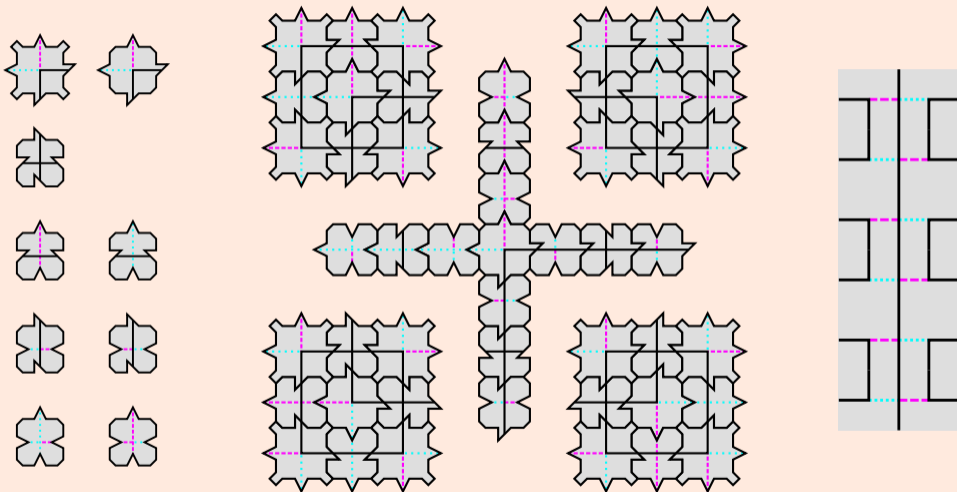


Figure 7: Tileset and hierarchical structure of the Robinson tiling, with strengthened local rules.

High-Density Quasi-Periodic Structure

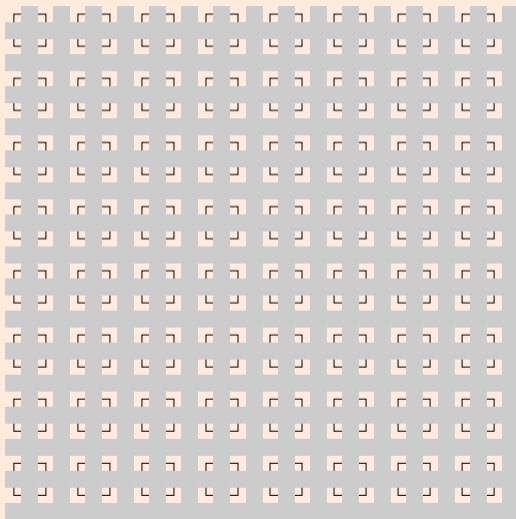


Figure 8: The density of the grid around N -macro-tiles goes to 0 as $N \rightarrow \infty$.

High-Density Quasi-Periodic Structure

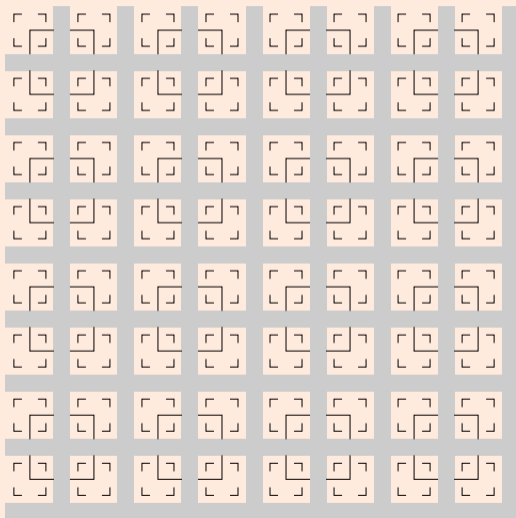


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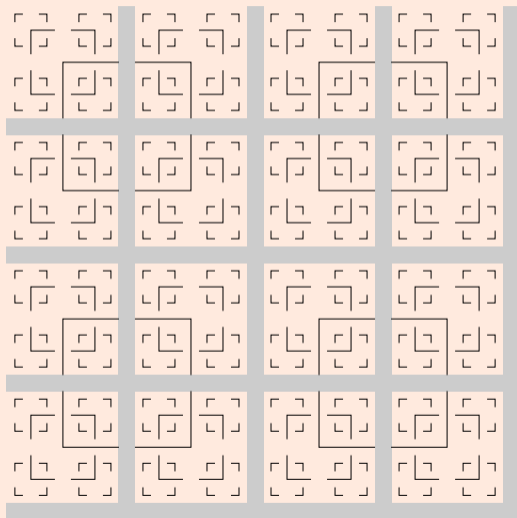


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Stability for Aperiodic Tilings

Aperiodic Stability

Reconstruction Function for the Enhanced Tiling

Proposition [Gayral and Sablik, 2021, Proposition 7.7]

For any scale $N \geq 2$, the constant $C_N = 2^N - 1$ is such that for any integer n and any clear locally admissible pattern w on B_{n+C_N} , $w|_{B_n}$ is almost globally admissible, in the sense that up to a low-density grid, $w|_{B_n}$ is made of well-aligned and well-oriented N -macro-tiles.

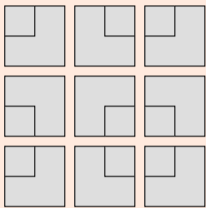


Figure 9: Family of well-aligned and well-oriented tiles.

Non-linear Polynomial Stability

Theorem [Gayral and Sablik, 2021, Proposition 7.8 and Theorem 7.9]

For any $\varepsilon > 0$, any scale N , and any measure $\mu = \pi_1^*(\lambda)$ with $\lambda \in \widetilde{\mathcal{M}}_{\mathcal{F}}^{\mathcal{B}}(\varepsilon)$:

$$d_B(\mu, \mathcal{M}_{\mathcal{F}}) \leq 96 (2^{N+2} + 1)^2 \varepsilon + \frac{1}{2^{N-1}}.$$

Hence, the SFT is f -stable with $f(\varepsilon) = 48\sqrt[3]{6\varepsilon}$.

Could we obtain faster bounds for an aperiodic tiling ?

Stability for Aperiodic Tilings

Aperiodic Unstability

A Two-Coloured Robinson Tiling

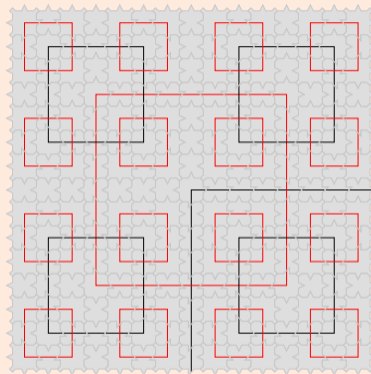
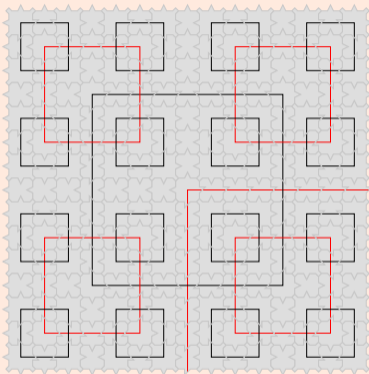
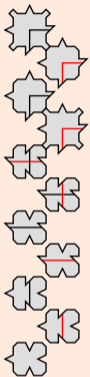


Figure 10: Two-coloured Robinson structure.

Unstable Colour Flips

Proposition [Gayral, 2021, Proposition 1]

The SFT Ω_{RB} is unstable.

More precisely, for any $\varepsilon > 0$, we have $\mu \in \mathcal{M}_{RB}^B(\varepsilon)$ such that $d_B(\mu, \mathcal{M}_{RB}) \geq \frac{1}{8}$.

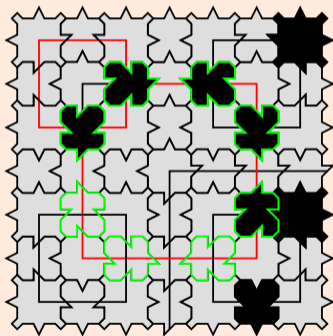


Figure 11: The Red-Black alternating structure allows for colour flips.

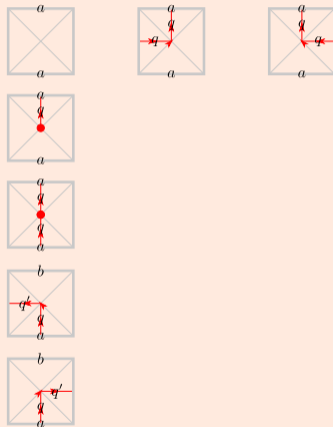
Undecidability of the Stability

Σ_1 -Hardness of the Problem

Turing Machine Space-Time Diagrams as Tilings

Consider a Turing machine $(Q, \Gamma, I, F, \delta)$ and define the following Wang tiles:

- For any letter $a \in \Gamma$ and any state $q \in Q$:
- For any letter $a \in \Gamma$ and initial state $q \in I$:
- For any letter $a \in \Gamma$ and final state $q \in F$:
- For any transition $\delta(a, q) = (b, q', L)$:
- For any transition $\delta(a, q) = (b, q', R)$:



Embedding Space-Time Diagrams into Robinson Tilings

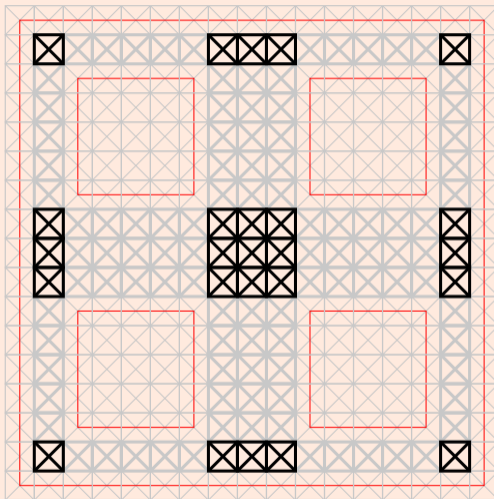


Figure 12: The free black tiles encode the diagram, the grey ones are communication channels.

A Four-Coloured Enhanced Robinson Tiling

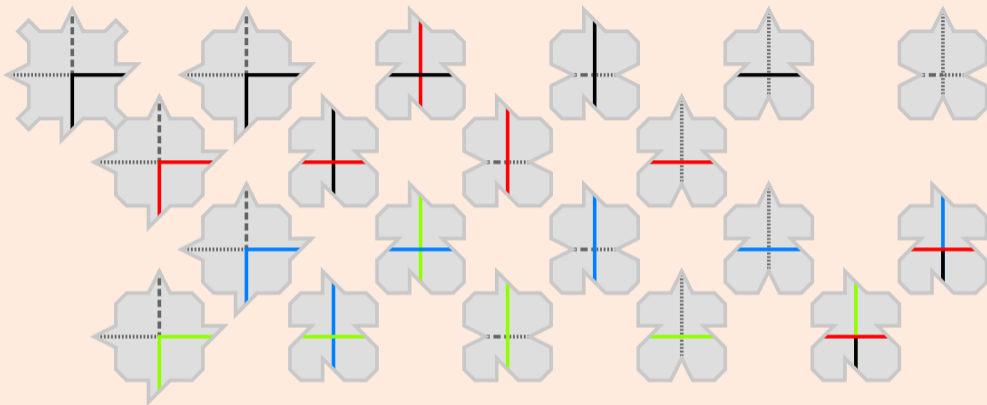


Figure 13: The tiling uses an enhanced Robinson structure. It starts with Black bumpy tiles, alternates between Red and Black, then may transition to an unstable Blue-Green regime.

Transition from the Red-Black to the Blue-Green Phase

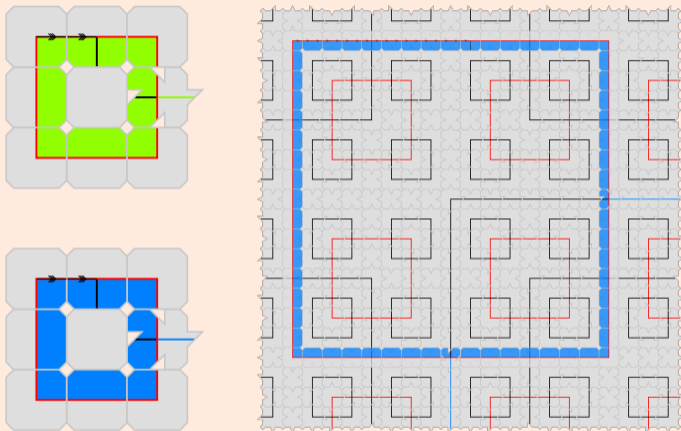


Figure 14: The flow layer appears *iff* there is a final state, and propagates the colour on the border.

Undecidability of the Stability

Theorem [Gayral, 2021, Theorem 1]

Denote \mathcal{F}_T the SFT that embeds the Turing machine T into a Robinson tiling.

Then \mathcal{F}_T is stable (for d_B on the class \mathcal{B}) iff T does not halt on the empty input.

In the stable case, \mathcal{F}_T is polynomially stable.

Because the halting problem is Σ_1 -hard, so is the question of unstability.

Theorem

Stability is Π_1 -hard.

Idea for the Stable Case: All N -Macro-Tiles Are Mostly the Same

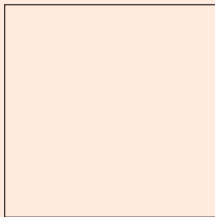


Figure 15: In a $2N$ -macro-tile, only $O(12^N)$ tiles out of 16^N are ignored.

This gives a $16^N \times C\varepsilon + \left(\frac{3}{4}\right)^N$ bound on d_B at scale $2N$.

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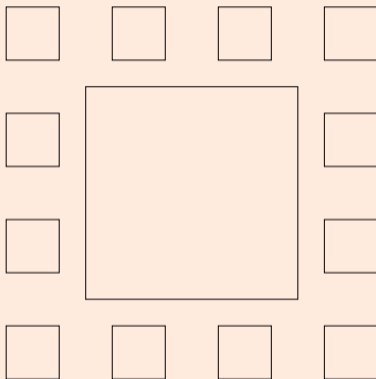


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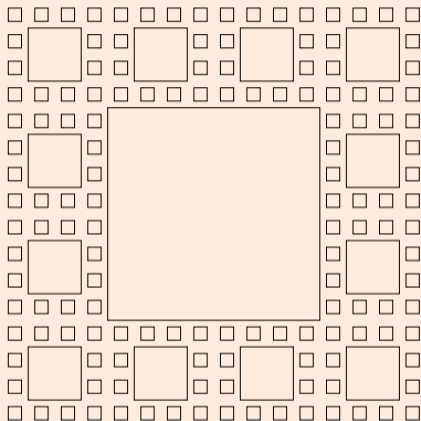


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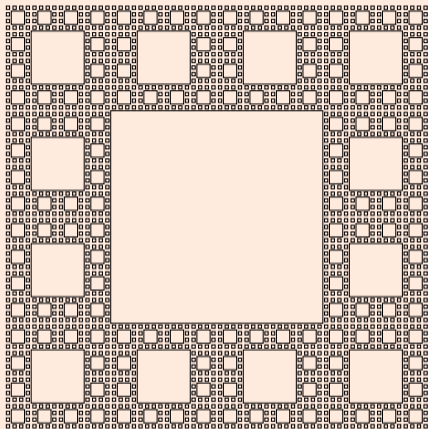


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Idea for the Unstable Case: Two Kinds of Widely Different N -Macro-Tiles

We can do the same Blue-Green colour flip as in our Red-Black unstable example.

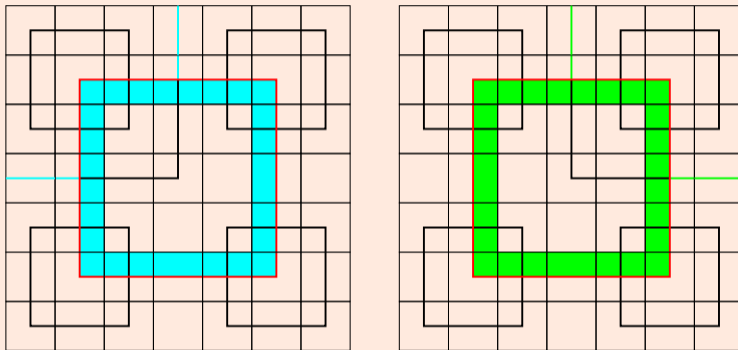


Figure 16: The transition scale plays the role of 1-macro-tiles for the Blue-Green phase.

If the Turing machine stops in the $2N$ -macro-tiles,

we guarantee a $\Omega\left(\frac{1}{16^N}\right)$ density of differences between Blue and Green.

Dual Construction for Σ_1 -Hard Stability

We now use the following Robinson structure:

- Encode two bits (a, b) in the central arm.
- The Red-Black bit a starts as Black and then alternates, for the Turing structure.
- The Blue-Green bit b starts freely and then alternates.
- Whenever the machine stops (necessarily a is Black), b *must* be Blue.

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Thence:

T halts	\Rightarrow	One kind of macro-tiles only at big-enough scales	\Rightarrow	Stable
T doesn't stop	\Rightarrow	Two kinds of different macro-tiles at all the scales	\Rightarrow	Unstable

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Stability is Σ_1 -hard.

Undecidability of the Stability

Climbing the Arithmetical Hierarchy

Toeplitz Encoding of a Sequence

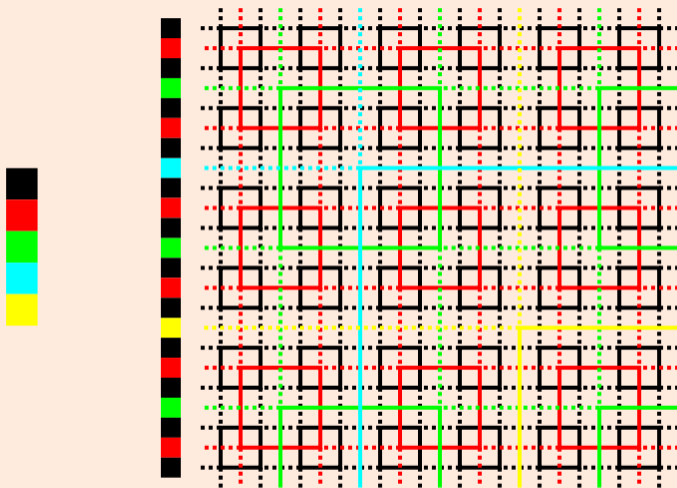


Figure 17: Toeplitz encoding of the sequence of colours on the left into the Robinson hierarchy.

Toeplitz Encoding of a Sequence

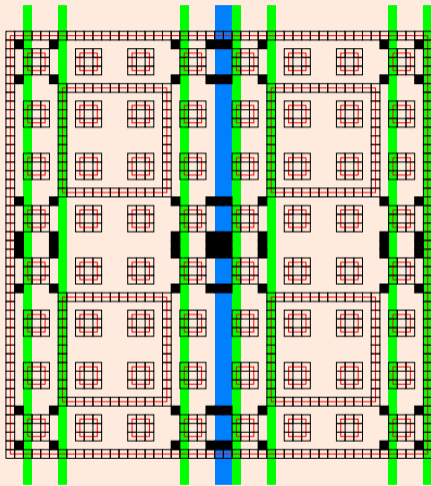


Figure 18: In practice, we see a finite prefix of the Toeplitz encoding as a read-only input.

Generalising the Σ_1 -Hard Construction on Toeplitz Inputs

Consider a Turing machine T with the alphabet $\Gamma = \Sigma \sqcup \{\#\}$.

We encode a word $w \in \Sigma^* \{\#\}^*$ of length N in a $(2N + 1)$ -macro-tile.

We have three phases in the Robinson hierarchy:

1. Decoding of the Toeplitz sequence into a word $w \in \Sigma^*$.



Ignition of the unstable Blue-Green bit.



2. Partial computation of T on the input w .



Freezing of the now stable Blue-Green bit.



3. T halts on w .

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Stability is Π_2 -Hard

We have 3 situations globally speaking:

- Infinite decoding of an input $w \in \Sigma^{\mathbb{N}}$: stable.
- Halting of T on $w \in \Sigma^*$: stable.
- Infinite computation of T on $w \in \Sigma^*$: unstable through colour flips.

We have a family of bounds of the form:

$$d_B(\mu_\varepsilon, \mathcal{M}_{\mathcal{F}_T}) \leq 16^{\varphi(N)} \times C\varepsilon + \left(\frac{3}{4}\right)^N,$$

with $\varphi(N)$ the scale at which T has halted on all the inputs of length at most N .

If T halts on all the inputs, the bound still goes to 0 as $\varepsilon \rightarrow 0$,
but cannot be explicit as φ can be bigger than any computable function.

Theorem

\mathcal{F}_T is stable iff T stops on all its entries, which is a Π_2 -complete problem.

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Undecidability of the Stability

Finding an Upper Bound

Could the Problem be Π_2 -Complete?

Stability of $\Omega_{\mathcal{F}}$: $\forall \varepsilon > 0, \exists \delta > 0, \sup_{\mu \in \mathcal{M}_{\mathcal{F}}^{\mathbb{B}}(\delta)} d_B(\mu, \mathcal{M}_{\mathcal{F}}) \leq \varepsilon.$

By monotonicity we can consider $\varepsilon, \delta \in \mathbb{Q}^{+*}.$

How could we decide $\sup_{\mu \in \mathcal{M}_{\mathcal{F}}^{\mathbb{B}}(\delta)} d_B(\mu, \mathcal{M}_{\mathcal{F}}) \leq \varepsilon?$ Is it in $\Sigma_1?$

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THE END OF PRESENTATION

ONE MORE SLIDE:

Thank you.